The Reaction Wheel Pendulum pdf

Mark Spong

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DESCRIPTION OF THE BOOK THE REACTION WHEEL PENDULUM

This monograph describes the Reaction Wheel Pendulum, the newest inverted-pendulum-like device for control education and research. We discuss the history and background of the reaction wheel pendulum and other similar experimental devices. We develop mathematical models of the reaction wheel pendulum in depth, including linear and nonlinear models, and models of the sensors and actuators that are used for feedback control. We treat various aspects of the control problem, from linear control of themotor, to stabilization of the pendulum about an equilibrium configuration using linear control, to the nonlinear control problem of swingup control. We also discuss hybrid and switching control, which is useful for switching between the swingup and balance controllers. We also discuss important practical issues such as friction modeling and friction compensation, quantization of sensor signals, and saturation. This monograph can be used as a supplement for courses in feedback control at the undergraduate level, courses in mechatronics, or courses in linear and nonlinear state space control at the graduate level. It can also be used as a laboratory manual and as a reference for research in nonlinear control.

THE REACTION WHEEL PENDULUM | SYNTHESIS LECTURES ON CONTROLS

Abstract. This monograph describes the Reaction Wheel Pendulum, the newest inverted-pendulum-like device for control education and research. We discuss the history and background of the reaction wheel pendulum and other similar experimental devices. From a mechanical standpoint, the Reaction Wheel Pendulum is a simple pendulum with a rotating wheel, or bob, at the end. The wheel is attached to the shaft of a 24-Volt, Self Balancing Stick - Dual Axis Reaction Wheel Inverted Pendulum. Copper's Surprising Reaction to Strong Magnets. Reaction Wheels. This monograph describes the Reaction Wheel Pendulum, the newest inverted-pendulum-like device for control education and research. We discuss the history and background of the reaction wheel pendulum and other similar experimental devices. The reaction wheel pendulum is one of the simplest non-linear underactuated systems. It is a pendulum with a rotating wheel at the end, which is free to spin about an axis parallel to the axis of rotation of the pendulum (see Figure 7.1). A Reaction Wheel Inverted Pendulum, I build as part of of my Master's Thesis in Advanced Control and Real-time Systems. Uses a Hybrid Control Law: The Reaction Wheel Pendulum is the newest and the simplest of the various pendulum experiments due to the symmetry of the wheel

attached to the end of the pendulum. The Pendubot is designed so that the axes of rotation of the two links are parallel while in the Rotary Pendulum. the axes of rotation are perpendicular. The Reaction Wheel Pendulum is shown schematically in Fig. 1. It is a physical pendulum with a symmetric disk attached to the end which is free to spin about an axis parallel to the axis of rotation of the pendulum. strategy for a 1D reaction wheel-based inverted pendulum. The authors are with the Institute for Dynamic Systems and Control, Swiss Federal Institute of Technology Zurich, Switzerland. Reaction wheels work on the principle of conservation of angular momentum. Accelerating the wheel in one direction also accelerates the stick in the opposite direction, such that the total angular momentum remains constant. Hello Everyone, I am working on a project to stabilize a reaction wheel pendulum.It is a type of inverted pendulum but unlike moving cart type this pendulum has a reaction wheel mounted on the top.Torque is produced by the change of the angular momentum of the reaction wheel. 1 1. Introduction The Reaction Wheel Pendulum (RWP) consists of a pendulum with a rotating wheel (rotor). The rotor is actuated by a 24 volt magnet DC motor mounted on the pendulum. This means that the inverted pendulum (second order), is controlled by another second order system (reaction wheel). Usually an inverted pendulum is controlled with a motor directly controlling the angle of the pendulum (i.e. pendulum attached to the motor shaft) which is a 1:1 relationship. I'm a little confused about the equations of motion of the reaction wheel pendulum. It is used in self balancing bicycles - see vide link in comments (I can't add another link here due to low rep).... Self Balancing Stick - [Dual Axis Reaction Wheel Inverted Pendulum] (self.arduino) submitted 3 years ago by vt2399 Here's a side project I have been working on using an Arduino.

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In this paper we introduce the Reaction Wheel Pendulum, a novel mechanical system consisting of a physical pendulum with a rotating bob. This system has several attractive features both from a. Hi, ihave a little problem for my final project about simulation reaction wheel using a matlab/ simulink. By the way, never heard 'reaction wheel', reaction wheel are modul used in sattelite or spacecraft to againt the action of sattelite body. Im very happy if you want to make my problem little. The Cubli: A Reaction Wheel Based 3D Inverted Pendulum Mohanarajah Gajamohan, Michael Muehlebach, Tobias Widmer, and Raffaello D'Andrea Abstract—The Cubli is a 15 15 15 cm cube with reaction Stabilizing an inverted pendulum by use of reaction wheels, makes for an interesting project that shows Newton's third law of motion applied to circular motion. This is a huge advantage over the reaction wheel pendulum, and the segway, which would require a proportional amount of power per unit torque desired from the balancing mechanism. The Reaction Wheel Pendulum is perhaps the simplest of the various pendulum systems in terms of its dynamic properties. At the same time, the Reaction Wheel Pendulum exhibits several properties, such as underactuation and nonlinearity that make it an attractive and useful system for research and advanced education. A reaction wheel (RW) is a type of flywheel used primarily by spacecraft for three axis attitude control, which doesn't require rockets or external applicators of torque. They provide a high pointing accuracy,: 362 and are particularly useful when the spacecraft must be rotated by very small amounts, such as keeping a telescope pointed at a star. I was able to use the the rate of

change of angle calculated by sampling position every 10 ms to swing up the reaction wheel pendulum. Like previous codes I used the bang bang energy controller with the energy based controller for the swing up. The Cubli: A Reaction Wheel Based 3D Inverted Pendulum Mohanarajah Gajamohan, Michael Muehlebach, Tobias Widmer, and Raffaello D'Andrea Abstract The Cubli is a 15 15 15 cm cube with reaction This monograph describes the Reaction Wheel Pendulum, the newest inverted-pendulum-like device for control education and research. We discuss the history and background of the reaction wheel pendulum and other similar experimental devices. The Reaction Wheel Pendulum (RWP) or also known as inertia wheel pendulum is a typical setup for education and demonstration in the ?eld of nonlinear control systems. The objective of this project is to investigate the stabilizing control of an inverted pendulum using the reaction wheel mechanism. A setup as shown in Fig.2 has been developed by some From a mechanical standpoint, the Reaction Wheel Pendulum is a simple pendulum with a rotating wheel, or bob, at the end. The wheel is attached to the shaft of a 24-Volt, permanent magnet DC… Balancing a one degree of freedom (DOF) inverted pendulum type structure using a reaction wheel is no new concept, and became more accessible with the introduction of inexpensive microcontrollers.

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